



# IMPORTANCE OF OCEAN OBSERVATIONS IN ECCC'S GLOBAL OCEAN ANALYSIS SYSTEM (GIOPS): A CONTRIBUTION TO THE SYNOBS PROJECT

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# THE UN DECADE SYNOBS PROJECT

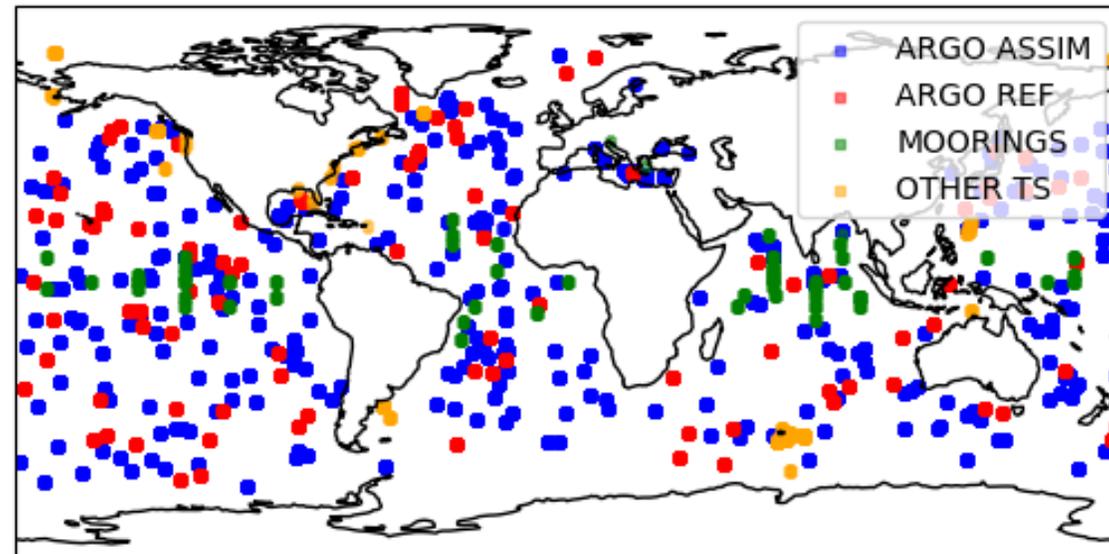
- The Synergistic Observing Network for Ocean Prediction (SynObs) project seeks to find synergies between ocean observations and ocean prediction through multi-system Observing System Experiments (OSEs).
    - <https://oceanpredict.org/synobs>
  - SynObs was proposed and designed to test the impact of different observing systems including in-situ T/S profile (Argo) observations as well as satellite SST and altimeter observations.
  - Here we assess the impact of SynObs OSEs on analysis error and the degradation in three user-relevant areas:
    - Shallow water ducts, representation of mesoscale eddies and surface drift
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# SYNOBS OSE EXPERIMENT DESIGN

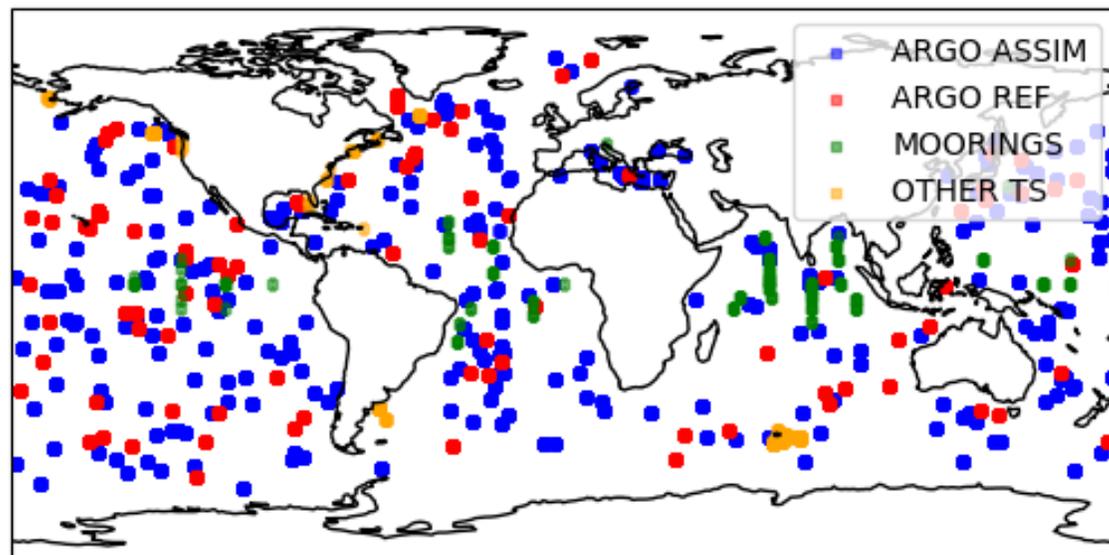
## Observing System Experiments

1	CNTL		SST	Argo 80%	Mooring	Other TS	Altimeter*
2	NoAlt		SST	Argo 80%	Mooring	Other TS	
3	NoArgo		SST		Mooring	Other TS	Altimeter*
4	NoMoor		SST	Argo 80%		Other TS	Altimeter*
5	NoSST			Argo 80%	Mooring	Other TS	Altimeter*
6	NoInsitu		SST				Altimeter*
7	SSTonly		SST				
8	Free						
9	HalfArgo		SST	Argo 40%	Mooring	Other TS	Altimeter*
10	Oper	Oper. Setting	SST	Argo 100%	Mooring	Other TS	Altimeter

T Observations for 20200101

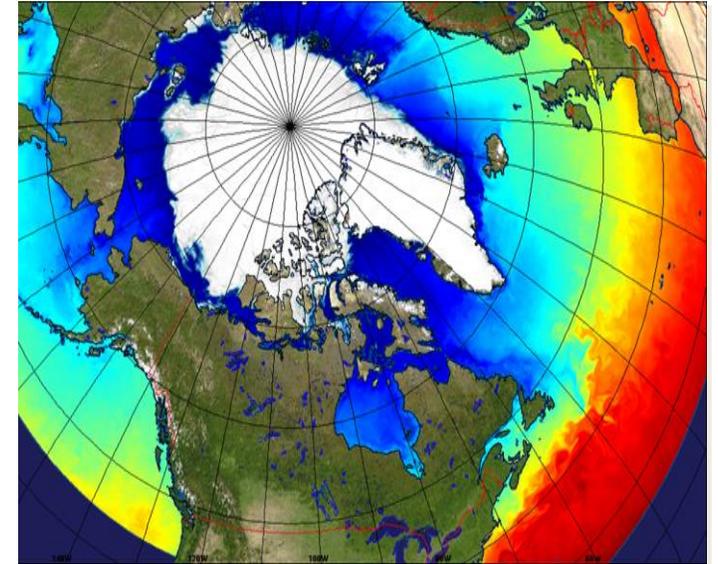


S Observations for 20200101



# GLOBAL ICE OCEAN PREDICTION SYSTEM (GIOPS)

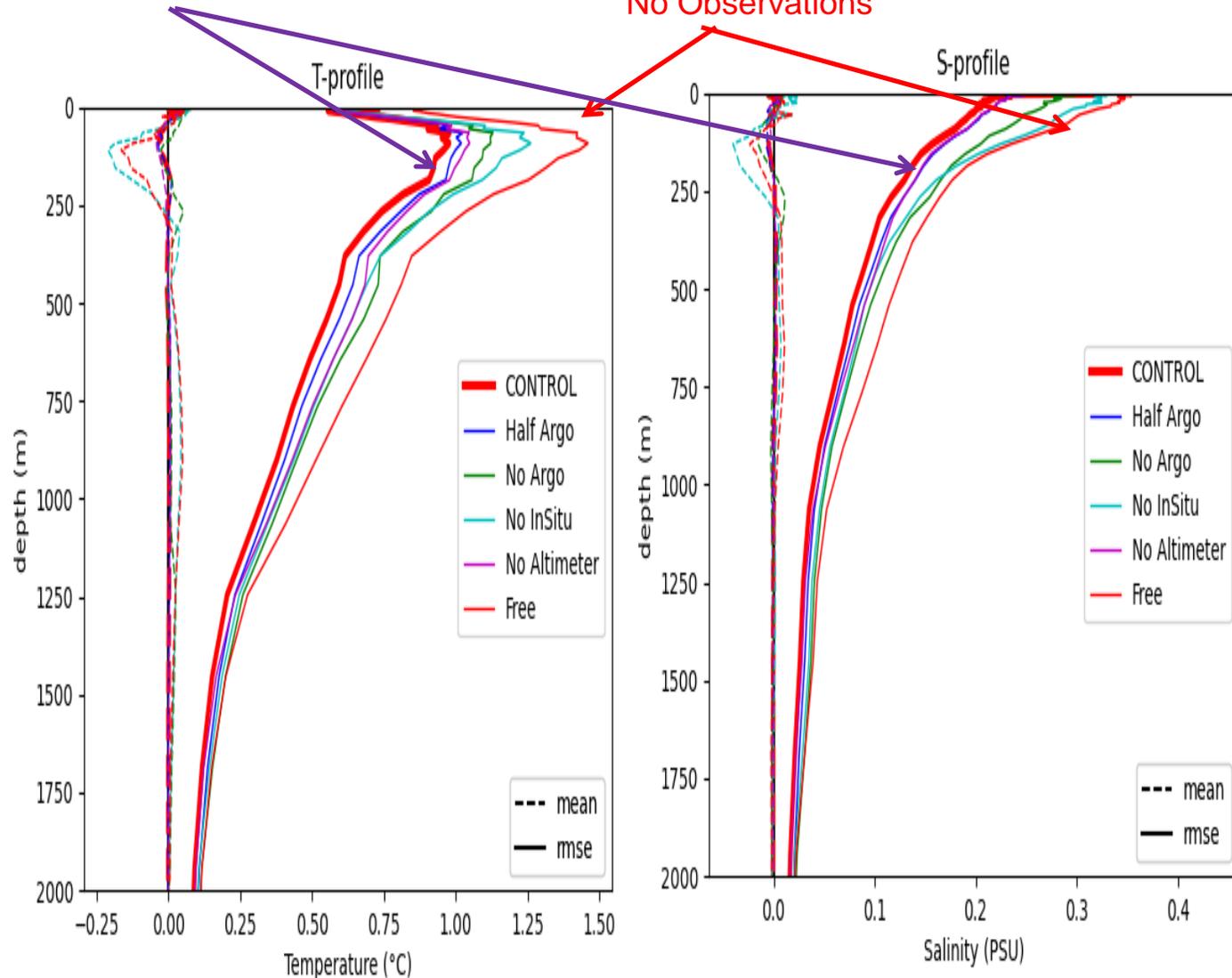
- Provides ECCO Global Ocean/Ice initial conditions
  - Ocean State Analysis for coupled 10d deterministic, 16/39d ensemble and seasonal forecasts
  - based on Mercator Assimilation System (SAM2v1)
  - Reduced-order extended Kalman filter
  - 3D-Var T/S bias correction term
  - 7-day assimilation window with 1-day IAU
- Observations assimilated:
  - T/S profile observations including Argo profiles
  - Along-track sea level anomaly (SLA).
  - CMC L4-SST analysis (satellite/in-situ data).
  - Blended with 3DVar sea ice analysis.
- For daily forecasts, 7x1d updates (SST/ice only) provide initial conditions



# IMPACT OF REMOVING ARGO

CNTL/80% ARGO

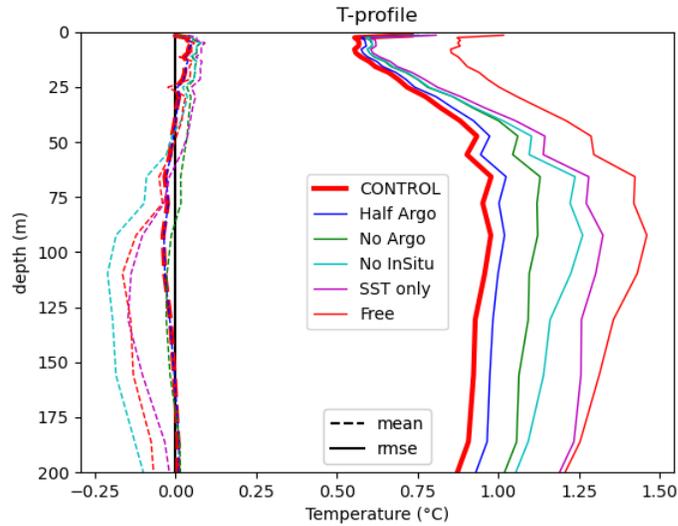
Free:  
No Observations



- CNTL (THICK) (80% Argo + all other observations)
- As **Argo** is taken away (HalfArgo --40% Argo; NoArgo – 0% Argo; NoInSitu) profile fits gets progressively worse and more like Free Run (thin).
- Except below 500m when NoInSitu better than NoArgo (more later).
- NoAlt is about as bad as NoArgo/NoInSitu below 500m
  - But profiles are important to get mix layer maximum error down.

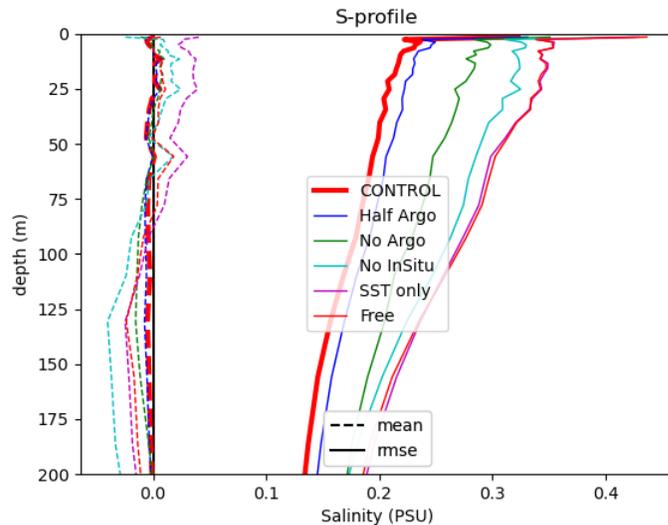
# IMPACT OF REMOVING SATELLITE SST/ALT

## T 0-200m



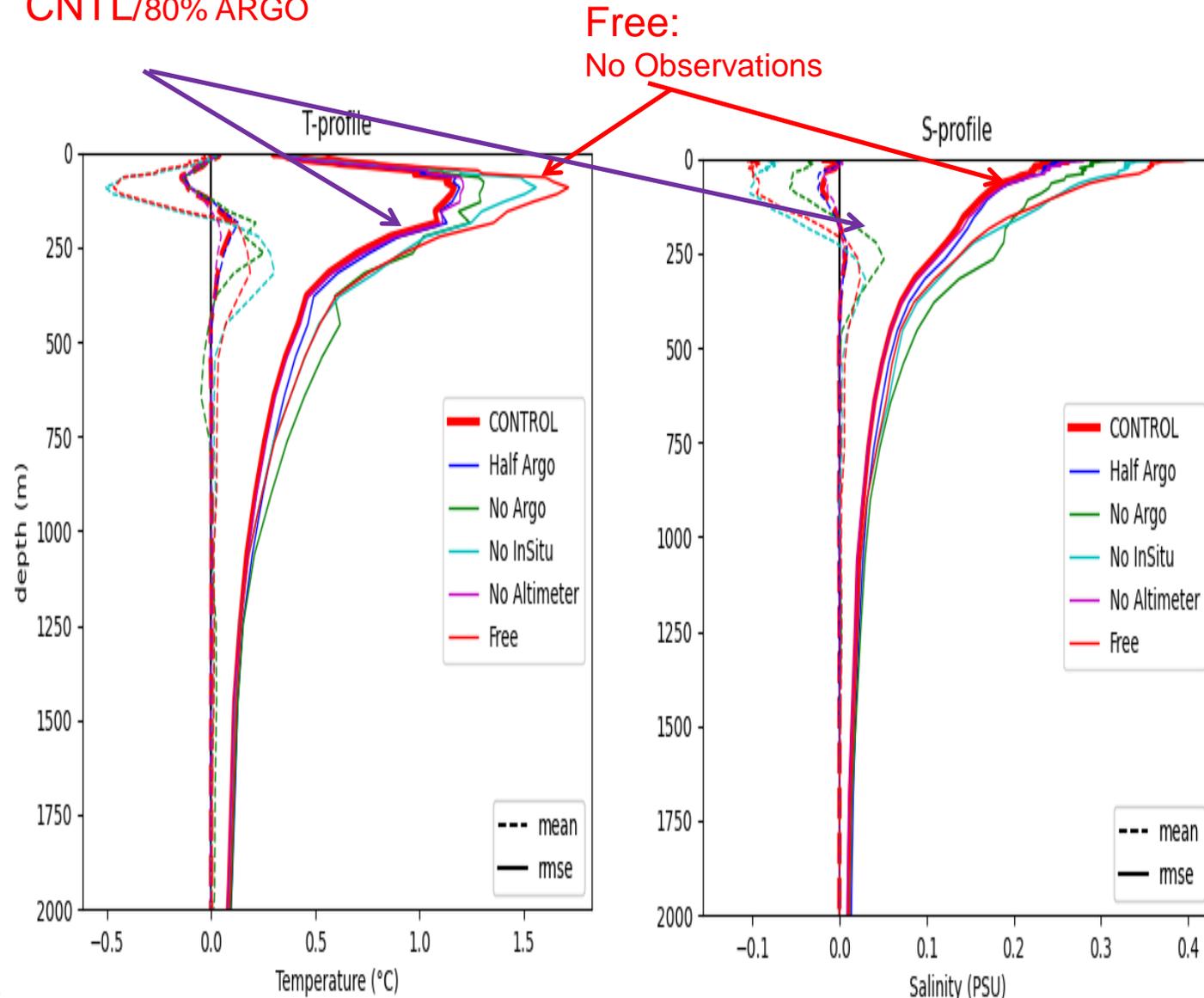
- Impact of SST (**SST only** / **Free** (thin) only in top 200m of T Profile
  - No influence on S Profile at all.
- **NoInSitu** (No T/S profiles but altimeter and SST obs)
  - 0-75m influence of **SST** (SST only)
  - > 100m influence of altimetry
  - **NoInSitu** maximum error ~100m shows importance of profiles to capture depth of mixed layer.

## S 0-200m



# IMPACT OF REMOVING ARGO IN TROPICS

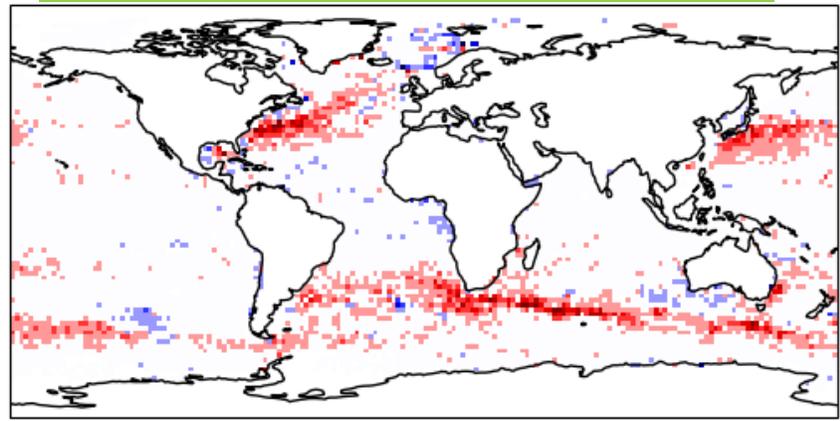
CNTL/80% ARGO



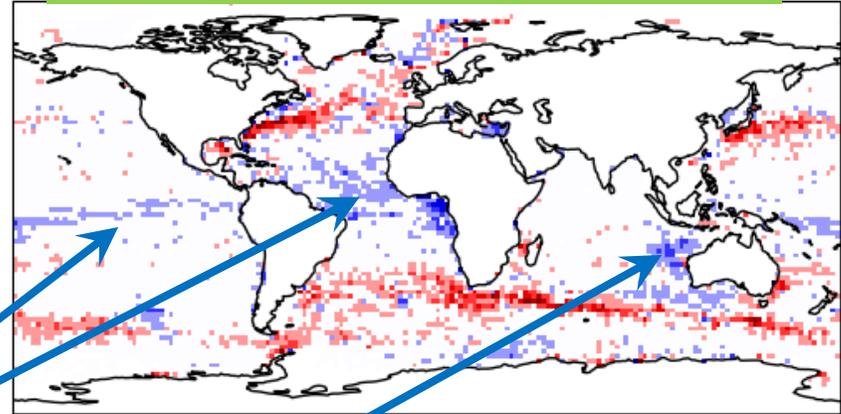
- In Tropics, have TAO/RAMA/PIRATA arrays – so ARGO should not matter as much.
- However, **NoARGO** gets as bad as **free** from 250m down.
- And worse than **free** below 500m
- Arrays only go down 500m!
- Below 250m **NoInSitu** == **Free**
  - **Altimeter** isn't helping much.

# IMPACT OF ARGO AND OTHER PROFILES ON DEEP WATER MASSES

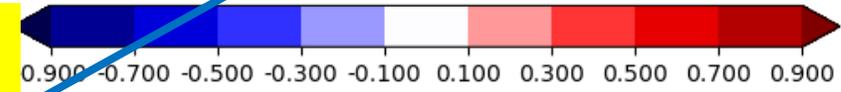
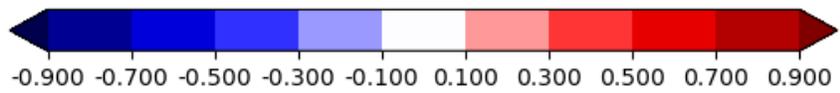
Add Altimeter and SST  
Free - NoIn situ



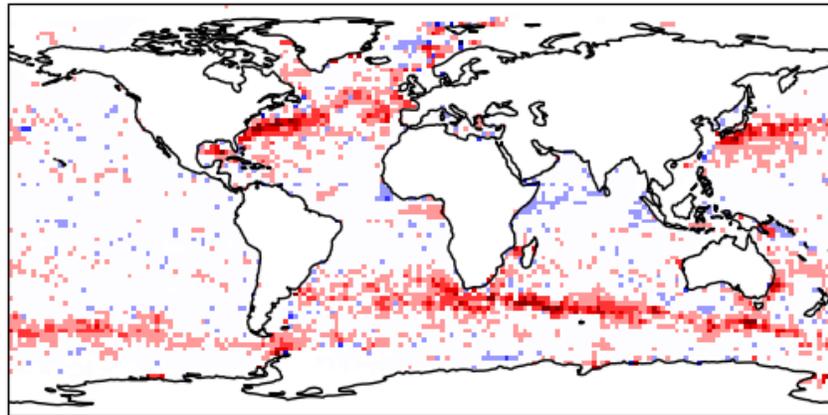
Further Add Non-Argo Profiles  
Free - NoArgo



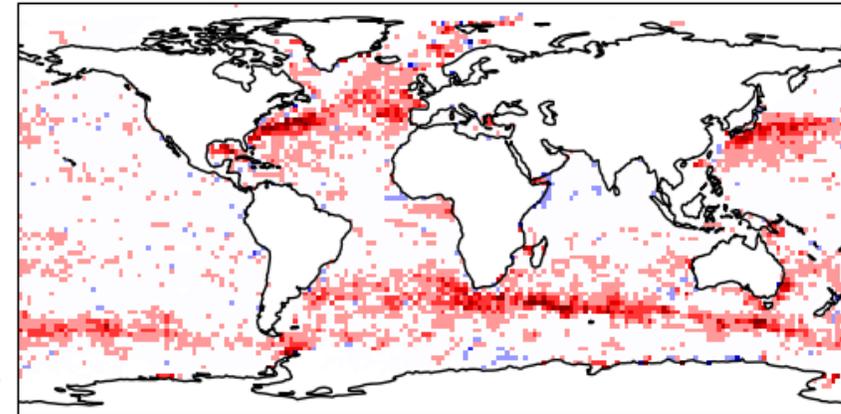
**Difference  
WRT  
Free  
RMSE**



Further Add 40% Argo  
Free - HalfArgo



Further add full 80% Argo  
Free - CNTL



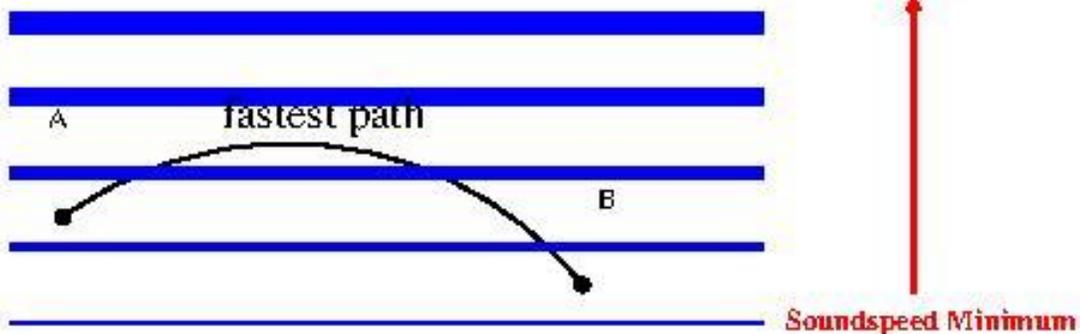
Only having observations (moorings) above 500m degrades solution below 500m

Upwelling also difficult  
RED == Improvement (RMS SMALLER)  
BLUE == Degradation (RMS Bigger)

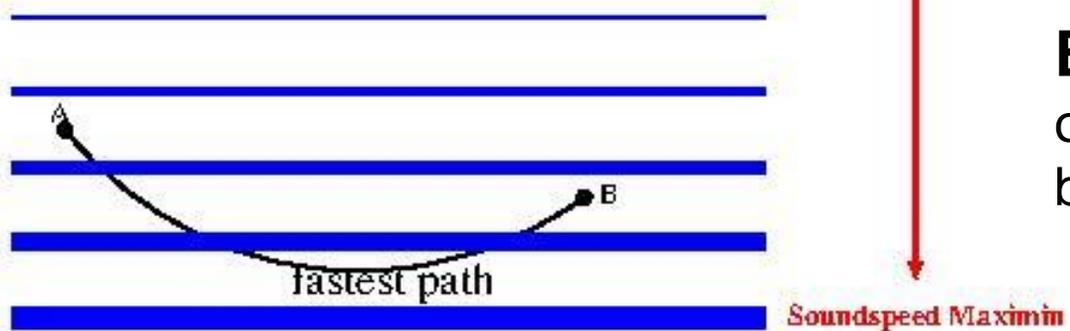
# SHALLOW WATER DUCTS

**Fermat's Principle:** Waves travel between two points along the path that requires the least time, as compared to other nearby paths

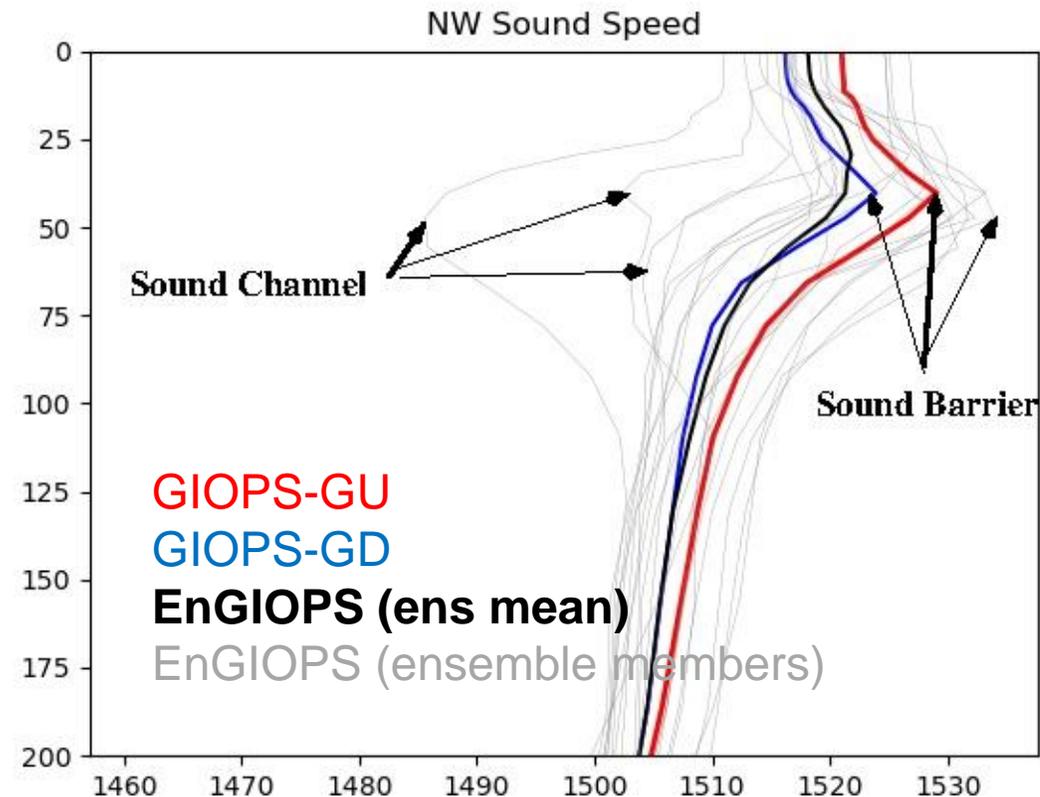
## Sound Channel



## Sound Barrier



Typical set of sound speed profiles for North Wall of Gulf Stream on 2020-10-09



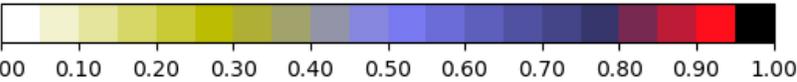
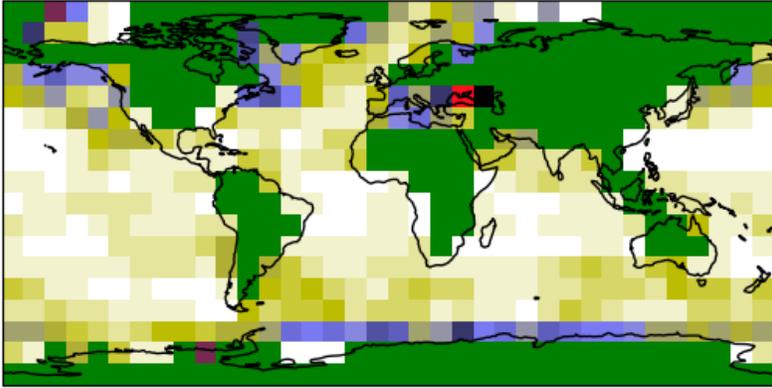
**Existence of Shallow Duct:** Determine if Model or Observation has local minimum in sound speed between 10-100m (using `scipy.signal.find_peaks`)

**Score:** Find Incorrect Forecasts:  $|M - O|$

0 == Correct 1 == Incorrect

## Observed Frequency

Probable Occurrence in Bin (glb.avg. = 0.171678448774151)

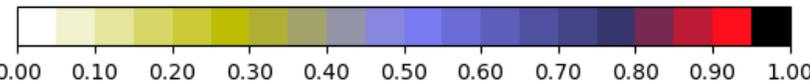
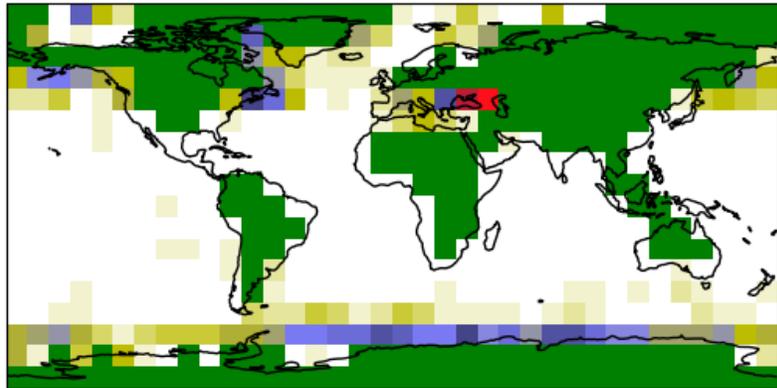


# SHALLOW WATER DUCTS

- See Tollefsen [2023]
  - <https://cradpdf.drdc-rddc.gc.ca/PDFS/unc423/p816498A1b.pdf>
- Measure of vertical gradients in T and S.
- Modelled Frequency of ducts roughly matches observed occurrence
  - At least in high latitudes / extra-tropics
- Missing something in tropics (surface salinity?)

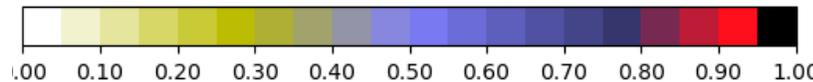
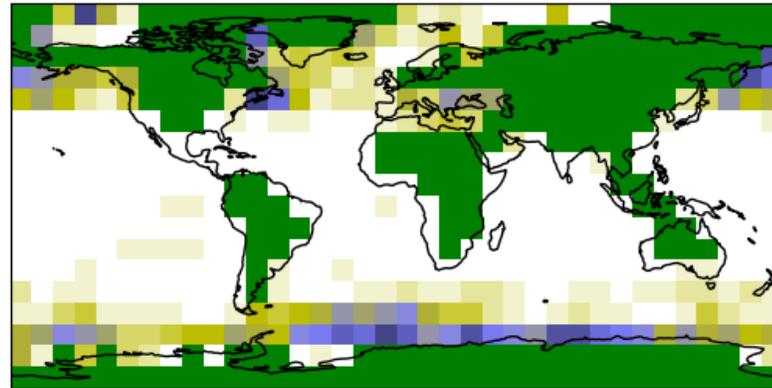
## Frequency in CNTL

Average Probability in Bin (glb.avg. = 0.08382213023416567)



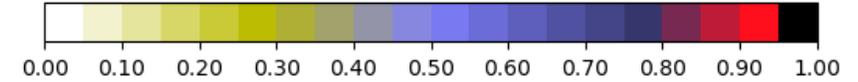
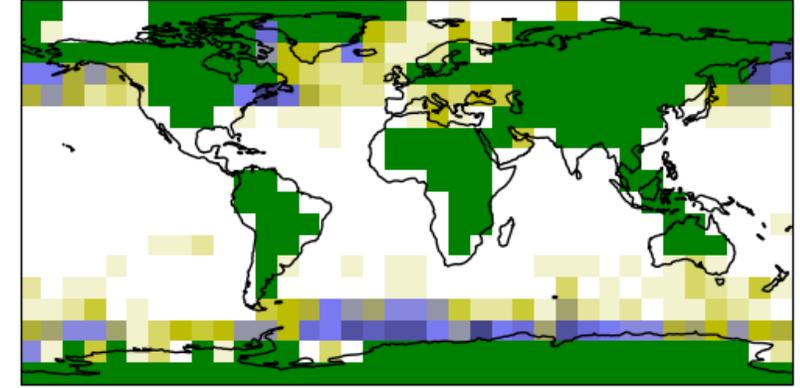
## Frequency in NoArgo

Average Probability in Bin (glb.avg. = 0.0954320911635187)



## Frequency in Free

Average Probability in Bin (glb.avg. = 0.10005025355201243)

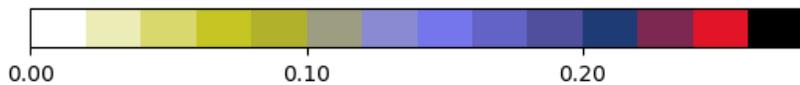
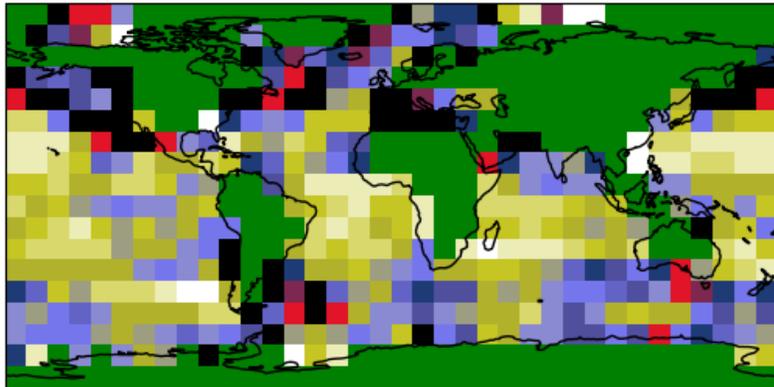


# SHALLOW WATER DUCTS

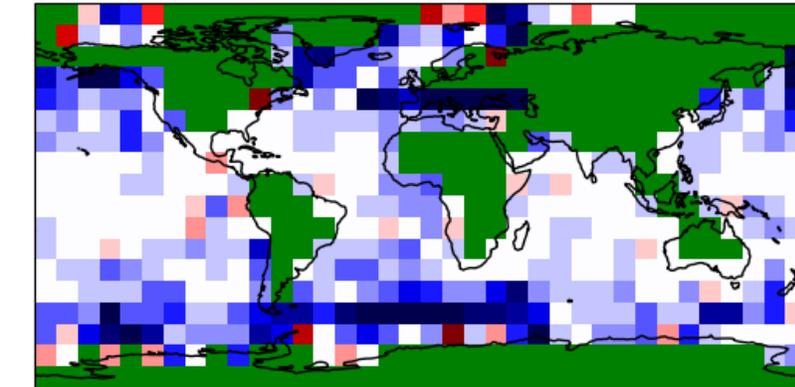
- Observations (CNTL vs Free) improve ability to detect sound channels.
- Profiles (NoArgo vs CNTL) and to lesser extent altimeter (NoAlt vs CNTL) provide information.
- Altimeter (NoAlt) provides about the same information as having half of ARGO array (HalfArgo)

EXPT	global
	% missed
CNTL	13.98
NoSST	14.08
NoAlt	14.39
HalfArgo	14.49
NoArgo	15.74
Free	16.29
SSTOnly	17.01

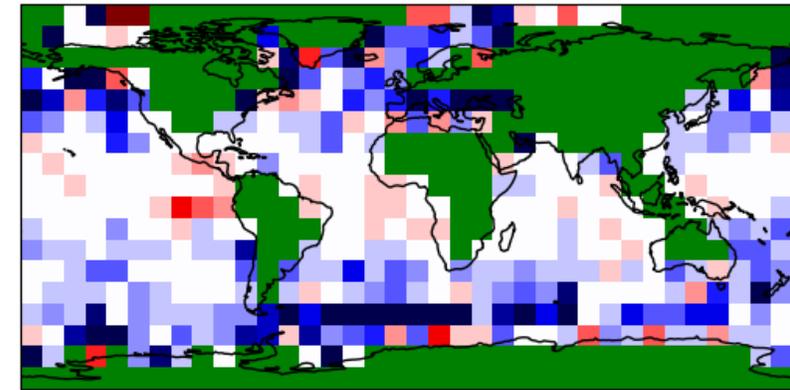
fraction missed in CNTL expt



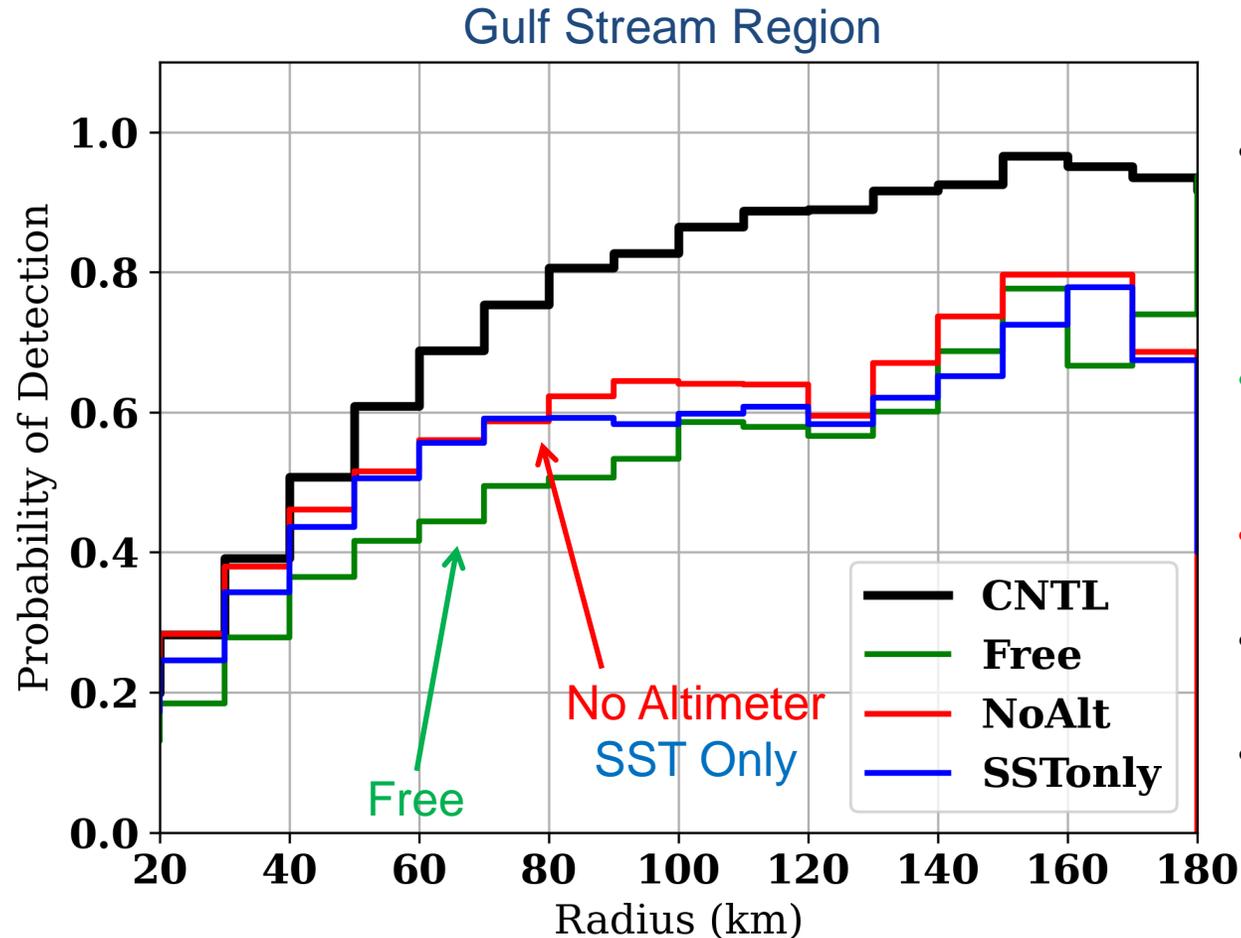
fraction missed in CNTL - NoArgo



fraction missed in CNTL - Free



# EDDY TRACKING



- Apply py-eddy tracker [Mason et al., 2014], a closed-contour approach over Northwest Atlantic
- Once eddies identified in obs (AVISO) find model matches using cost function based on amplitude, radius and distance.
- **Free Run** – should be random (but up to 80% detection).
  - **RANDOM BASELINE**
- **Removing Altimeter (NoAlt vs CNTL)** removes most of ability to detect eddies.
- But eddies < 100km are still detected (**NoAlt vs Free**)
- Position of small eddies are being given through the **SST (SST only)** observations.
  - **NoAlt (SST+Insitu)**
  - **SSTonly (only SST)**
- Profile data (**NoAlt**) may contribute to the detection of larger eddies (but the statistical significance is weak),.



See Smith and Fortin [2022]

<https://doi.org/10.1016/j.ocemod.2022.101982>

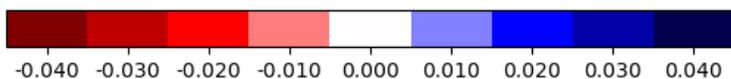
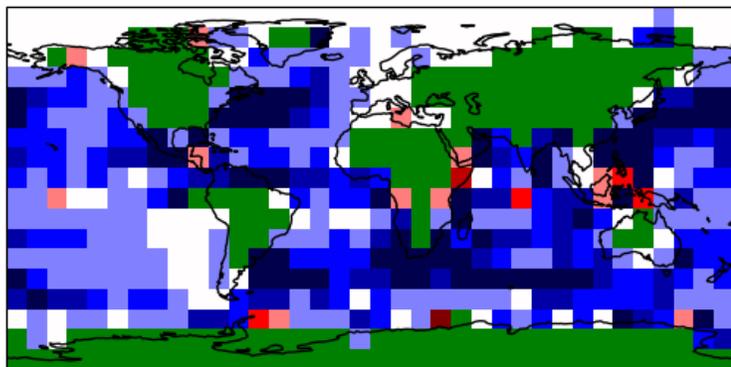
# CURRENT VALIDATION

EXPT	Speed	U	V
	rmse	rmse	rmse
	m/s	m/s	m/s
CNTL	0.1472	0.1490	0.1413
SSTonly	0.1666	0.1693	0.1592
NoAlt	0.1611	0.1724	0.1647
Free	0.1734	0.1748	0.1655

- **Comparison against 15-m drogued drifters (as in Aijaz et al., 2023)**
- **Removing Altimeter** (both NoAlt and SSTonly; Note: NoAlt == SST+insitu T/S) substantially reduces ability to predict currents.

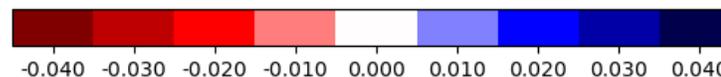
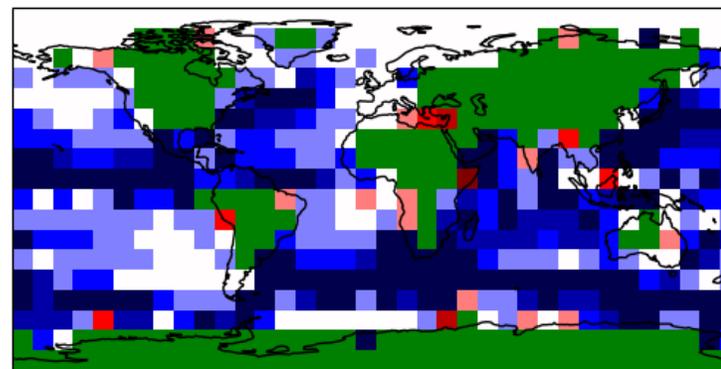
U RMSE difference NoAlt - CNTL

RMSE difference NoAltV2 (0.1724) - CNTLV2 (0.1490) init U



U RMSE difference Free - CNTL

RMSE difference Free (0.1748) - CNTLV2 (0.1490) init U



# SUMMARY

- ECCC is participating in OceanPredict SynObs project to investigate importance of various observing systems to ocean analysis systems.
- We have finished all observing system (OSE) data withholding experiments using GIOPS system.
- Initial results show importance of each of the in-situ profile, altimeter and SST observations.
- Novel and independent validation techniques can show importance of observations beyond just testing fits against observations.
  - Eddy tracking and Current Verifications show importance of Altimeter with secondary importance of SST observations.
  - Ability to detect shallow water ducts – and therefore gradients in T/S profiles shows importance of assimilating profiles with secondary importance of altimeter observations.

